AN UNEXPECTED CONNECTION BETWEEN BRANCHING PROCESSES AND OPTIMAL STOPPING

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Abstract

A curious connection exists between the theory of optimal stopping for independent random variables, and branching processes. In particular, for the branching process Z_n with offspring distribution Y, there exists a random variable X such that the probability $P(Z_n = 0)$ of extinction of the nth generation in the branching process equals the value obtained by optimally stopping the sequence $X_1, \ldots, X_n$, where these variables are i.i.d. distributed as X. Generalizations to the inhomogeneous and infinite horizon cases are also considered. This correspondence furnishes a simple 'stopping rule' method for computing various characteristics of branching processes, including rates of convergence of the nth generation's extinction probability to the eventual extinction probability, for the supercritical, critical and subcritical Galton–Watson process. Examples, bounds, further generalizations and a connection to classical prophet inequalities are presented. Throughout, the aim is to show how this unexpected connection can be used to translate methods from one area of applied probability to another, rather than to provide the most general results.

Keywords: Optimal stopping problem; Galton–Watson process; extinction probability; varying environment; inhomogeneous Galton–Watson process; prophet inequalities

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1. Introduction and summary

The purpose of the present note is to highlight what we believe to be a hitherto unnoticed connection between two seemingly unrelated topics in applied probability: optimal stopping theory for independent random variables, and branching processes and their extinction probabilities. We show how results in one area can be used to easily establish results in the other. Our main result is based on a mapping $Y \to X$ from integer valued offspring distributions to a distribution on $[0, 1]$ such that the probability of extinction by generation n of the Galton–Watson branching process with offspring distribution Y equals the value obtained by optimally stopping a sequence of n independent variables distributed as X. This correspondence is purely analytic, and in particular, we are not able to present a probabilistic reason, such as a coupling, which explains it. As the focus is on the 'unexplained' connection, in exploiting the analytic

equivalence of the two areas we do not strive for the most general results, but rather emphasize how one area can inform another area which is seemingly unrelated.

In Section 2 we outline the basic concepts needed from each of the two topics. In Section 3 we present our main result, a mapping $Y \rightarrow X$, from integer valued offspring distributions to distributions on [0,1] such that the probability of extinction by generation n of the Galton–Watson branching process with offspring distribution Y equals the value obtained by optimally stopping a sequence of n independent variables distributed as X. Examples of this correspondence are given in Section 4. Section 5 is devoted to proving, by means of 'stopping rule' methods, various (known) results on rates of convergence of the probabilities of extinction of the nth generation, denoted q_n, to the eventual probability of extinction, π, in the subcritical, critical and supercritical cases of the Galton–Watson process. In Section 6 we generalize the results to 'inhomogeneous' Galton–Watson processes, and provide examples. In Section 7 we show, in the inhomogeneous case, how the use of sub-optimal stopping rules and prophet inequalities may provide bounds on branching process extinction probabilities, and explore further connections to the prophet value.

2. Basic concepts

2.1. Optimal stopping theory

Consider a sequence $X_1, X_2, \ldots, X_n$ of independent random variables with known distributions. A statistician gets to view the values sequentially, and at each stage must decide whether to take the present variable or continue. Exactly one variable must be selected; there is no recall, and hence a variable which has been passed up is no longer available at a later stage to the statistician. The goal of the statistician is to pick as large a value as possible. If stopping has not occurred before time n the variable X_n is automatically selected. The number of variables, n, is called the horizon of the problem. The value to the statistician using a stopping rule t is

$$EX_t = E \sum_{i=1}^{n} X_i \mathbf{1}(t = i), \tag{2.1}$$

where $\mathbf{1}$ is the indicator function. The goal is to maximize the value in (2.1) over all possible stopping rules.

The general theory of optimal stopping is developed in Chow *et al.* (1971). For the finite horizon case an optimal rule always exists and can be obtained by backward induction. (See Theorem 3.2, p. 50 of Chow *et al.* (1971).) In the case of independent random variables the optimal rule has a particularly simple form. Let V_i^n be the value obtained by optimally stopping the sequence $X_i, \ldots, X_n$; since stopping must occur at or before time n we set $V_{n+1}^n = -\infty$. If stopping has not occurred by time i, it is optimal to choose X_i only if it is better than or equal to what is expected in the future. That is, if $X_i \geq V_{i+1}^n$ the value X_i is selected, and passed up otherwise. Hence, the value V_i^n is the expectation of the larger of X_i and V_{i+1}^n, that is,

$$V_i^n = E[X_i \vee V_{i+1}^n].$$

Alternatively, letting

$$h_i(a) = E[X_i \vee a] \tag{2.2}$$

we may write the following recursion for the sequence of values V_i^n;

$$V_i^n = h_i(V_{i+1}^n), \quad i = n, n-1, \ldots, 1. \tag{2.3}$$

An optimal stopping rule is

$$t_n^* = \min\{i : X_i \geq V_{i+1}^n\}. \tag{2.4}$$

Note that t_n^* will definitely stop by time n, if it has not stopped earlier. The value of this rule to the statistician is given by V_1^n. In the case where $X_n \geq 0$, $V_{n+1}^n = -\infty$ can be replaced by $V_{n+1}^n = 0$. The case where the X_i's are non-negative and i.i.d. is of particular interest. In this case h_i in (2.2) does not depend on i, and the index i will be omitted. Letting

$$h^{(1)}(a) = h(a) \quad \text{and} \quad h^{(n+1)}(a) = h(h^{(n)}(a)), \quad n = 1, 2, \ldots, \tag{2.5}$$

we have

$$V_1^n = h(V_2^n) = h^{(2)}(V_3^n) = \cdots = h^{(n)}(0).$$

If we let V_k denote the value for a k-horizon problem, then $V_i^n = V_{n-i+1}, i = 1, \ldots, n$, and

$$V_k = h^{(k)}(0), \quad k = 1, 2, \ldots. \tag{2.6}$$

For an infinite horizon problem in this i.i.d. setting, the value $V_\infty = \lim_{n \to \infty} V_n$ is the supremum over all stopping rules t with $P(t < \infty) = 1$. It equals the rightmost value of the support of X, that is, the essential supremum of X. An optimal rule achieving V_∞ will, however, not exist unless X attains this value with positive probability.

2.2. The Galton–Watson branching process

Let $\mathcal{Y}$ be the set of all non-negative, non-degenerate integer valued random variables excluding the variables for which $P(Y = 0) = 0$. For $Y \in \mathcal{Y}$ let $p_k = P(Y = k), k = 0, 1, \ldots$ and

$$g(s) = \sum_{k=0}^{\infty} p_k s^k \tag{2.7}$$

be the generating function of Y, which is well defined for $0 \leq s \leq 1$, with $g(0) = p_0$ and $g(1) = 1$. Note that if $EY < \infty$ then $g'(1) = EY$, and if $EY^2 < \infty$ then $g''(1) = EY^2 - EY$. All derivatives of $g(s)$ for $s \in [0, 1)$ exist and are non-negative, thus in particular $g(s)$ is increasing and convex; the function g will be strictly convex unless it is linear, that is, unless $p_0 + p_1 = 1$.

For given $Y_n \in \mathcal{Y}$, $n = 1, 2, \ldots$, define the (inhomogeneous, or varying environments) Galton–Watson branching process, with offspring distribution Y_n at generation n, as the discrete time stochastic process $\{Z_n\}_{n=0}^{\infty}$ with $Z_0 = 1$ and

$$Z_{n+1} = \sum_{i=1}^{Z_n} W_{ni}, \tag{2.8}$$

where W_{ni} are i.i.d. distributed like Y_n. The value Z_n is the size of the nth generation of a population which begins with a single individual at time 0, where each member of generation n gives rise to offspring for the next generation with distribution Y_n, independently of all the other members. Letting $g^{(n)}$ be the generating function of Z_n, and g_n be the generating function of Y_n, we have the well-known relation

$$g^{(n)}(s) = g_1(g_2(\cdots g_n(s))), \tag{2.9}$$

which can be verified by induction. A quantity of major interest is the probability that the nth generation is extinct

$$P(Z_n = 0) = g^{(n)}(0) = \tilde{q}_n. \qquad (2.10)$$

Since $Z_n = 0$ implies $Z_{n+1} = 0$, we have $0 \le \tilde{q}_1 \le \tilde{q}_2 \le \ldots$, and thus $\lim_{n \to \infty} \tilde{q}_n = \tilde{\pi} \le 1$ exists. The limit $\tilde{\pi}$ is the probability of eventual extinction. Furthermore, it is easily seen that EZ_n, the expected size of generation n, equals $\prod_{j=1}^{n} EY_j$. This follows by computing $[g^{(n)}]'(1)$ in (2.9) and using $g_j(1) = 1$.

When all the Y_n have identical distributions with generating function g,

$$g^{(1)}(s) = g(s), \qquad g^{(n+1)}(s) = g(g^{(n)}(s)), \qquad n = 1, 2, \ldots, \qquad (2.11)$$

and we denote $q_n = P(Z_n = 0) = g^{(n)}(0)$, and $\lim_{n \to \infty} q_n = \pi$. As is well known (see Karlin and Taylor (1975), Chapter 8) in this instance π is the smallest root of the equation

$$g(s) = s. \qquad (2.12)$$

The value $s = 1$ is always a root of (2.12), and it is the smallest root if and only if $EY < 1$ (the subcritical case), or $EY = 1$ (the critical case). There is positive probability of never becoming extinct, that is, of having $\pi < 1$, if and only if $EY > 1$ (the supercritical case).

3. Connection

Our main result in the present section is to exhibit the connection between optimal stopping and homogeneous Galton–Watson processes. In particular we link the optimal stopping value V_n to the extinction probability q_n using the following theorem.

Theorem 3.1. *Let $Y \in \mathcal{Y}$ have generating function g, and let π be the smallest root of the equation $g(s) = s$. Then the function $F(x)$ given by*

$$F(x) = \begin{cases} 0 & x < 0 \\ g'(x) & 0 \le x < \pi \\ 1 & \pi \le x, \end{cases} \qquad (3.1)$$

is a distribution function. Let X have distribution (3.1), and $h(a) = E[X \vee a]$. Then

$$h(a) = g(a) \quad \text{for} \quad 0 \le a \le \pi. \qquad (3.2)$$

Also

$$EX = P(Y = 0), \quad P(X = 0) = P(Y = 1) \quad \text{and when} \quad \pi = 1, \quad P(X < 1) = EY. \qquad (3.3)$$

The variable X has an atom of size $P(Y = 1)$ at 0, an atom of size $1 - g'(\pi)$ at π, and density $g''(x)$ on $(0, \pi)$. Exactly one distribution satisfies (3.2).

Proof. The function $g'(x)$ is non-negative and non-decreasing for $0 \le x \le \pi$. Note that $g'(\pi) \le 1$, since g is convex and $s < g(s)$ for all $0 \le s < \pi$. Further, by definition, for $0 \le a \le \pi$,

$$h(a) = E[X \vee a] = \int_0^\infty P([X \vee a] > x) \, dx = \pi - \int_a^\pi g'(x) \, dx = \pi - g(\pi) + g(a) = g(a),$$

which is (3.2). For $a = 0$, (3.2) yields $h(0) = g(0)$, or $EX = P(Y = 0)$, and $P(X = 0) = g'(0) = P(Y = 1)$. When $\pi = 1$, $EY \le 1$ and (3.1) yields $EY = g'(1) = F(1^-) = P(X < 1)$.

To show uniqueness, suppose (3.2) holds for some X^* with distribution function F^*. Since $\pi = g(\pi) = h(\pi) = E[X^* \vee \pi]$, it follows that $P(X^* > \pi) = 0$, i.e. $F^*(x) = 1$ for all $x \ge \pi$. Also, since g is differentiable in $0 < s < \pi$, so is h. But for $0 \le s \le \pi$, $h(s) = E[X^* \vee s] = 1 - \int_s^1 F^*(x)\,dx = g(s)$, thus $g'(s) = F^*(s)$ for $0 < s < \pi$, and thus, by right continuity, $F^*(x) = F(x)$ for all x.

Theorem 3.2. *Let Z_n be a Galton–Watson process with offspring distribution $Y \in \mathcal{Y}$, and extinction probability $q_n = P(Z_n = 0)$. Let $X_1, \ldots, X_n$ be i.i.d. with distribution function (3.1), and let V_n be its optimal stopping value. Then,*

$$V_n = q_n, \quad n = 1, 2, \ldots \tag{3.4}$$

Proof. For $0 \le a \le \pi$ we have $0 \le g(a) \le \pi$. By (3.2) and induction,

$$h^{(n)}(a) = g^{(n)}(a) \quad \text{for} \quad 0 \le a \le \pi. \tag{3.5}$$

Using (2.6) and (2.10) and setting $a = 0$ in (3.5) yields (3.4).

Remark 3.1. Equality (3.2) cannot hold for $\pi < a < 1$ since in this interval $g(a) < a$, while $h(a) = E[X \vee a] \ge a$.

Remark 3.2. The distribution of Y is uniquely determined by the sequence $\{q_n\}_1^\infty$, since an analytic function g is uniquely determined by its values on an infinite sequence of values having a limit point. Thus there are no two different Y's with the same q_n-sequence.

Remark 3.3. In contrast to Remark 3.2, there are many different i.i.d. sequences of X's with values $\{V_n\}_1^\infty$. For a construction, see Hill and Kertz (1982).

Remark 3.4. We excluded from $\mathcal{Y}$ the variables for which $P(Y = 0) = 0$. For such variables $\pi = 0$ is the smallest root of (2.12). Note that for this case F of (3.1) gives unit mass to 0, thus (3.2) and (3.4) are formally true also for this case.

Remark 3.5. Theorem 3.1 shows that for each $Y \in \mathcal{Y}$ there exists an X taking values in [0,1] such that (3.2) holds. However, it is not true that for each X taking values in [0,1] there exists a corresponding $Y \in \mathcal{Y}$. Necessary and sufficient conditions for X to correspond to a $Y \in \mathcal{Y}$ is that X has a distribution function F of the form

$$F(x) = \begin{cases} 0 & x < 0 \\ k(x) & 0 \le x < \pi \\ 1 & \pi \le x, \end{cases} \tag{3.6}$$

for some $0 < \pi \le 1$, and that (i) $k(\ )$ has a power series expansion with all coefficients non-negative, and (ii) There exists a constant $c > 0$ such that $g(s) = \int_0^s k(x)\,dx + c$ satisfies (a) $g(1) = 1$, (b) $g(\pi) = \pi$. This fact suggests that it will be easier to use the correspondence to translate properties of optimal stopping into properties about Galton–Watson processes, than vice versa.

4. Examples

The correspondence between Y and X of (3.1), yields some interesting relationships.

Example 4.1. $Y \sim \mathcal{B}(p)$ Bernoulli. In this case $P(Y = 1) = p = 1 - P(Y = 0)$ and clearly $\pi = 1$. As $g(s) = (1 - p) + ps$, $F(s) = p$ for $0 \le s < 1$, and $F(1) = 1$. Hence, $X \sim \mathcal{B}(1 - p)$.

Example 4.2. $Y \sim m\mathcal{B}(p)$, $m \ge 2$, that is, $P(Y = m) = p = 1 - P(Y = 0)$, $g(s) = (1 - p) + ps^m$, and $EY = mp$. Using (3.3), since $P(Y = 1) = 0$, X has no mass at zero, but has mass $1 - g'(\pi) = 1 - mp\pi^{m-1}$ at π. Therefore, for $0 \le s \le \pi$,

$$F(s) = mp\pi^{m-1} \left(\frac{s}{\pi}\right)^{m-1} + \mathbf{1}(s = \pi)(1 - mp\pi^{m-1}),$$

that is, X is a mixture of $\max_{i=1,\dots,m-1} U_i$, where U_i are i.i.d. $U(0, \pi)$, with probability $mp\pi^{m-1}$, and a point mass at π with probability $1 - mp\pi^{m-1}$. In particular, for $m = 2$ (corresponding to a splitting of a cell), in the critical case $p = 1/2$, $X \sim U(0, 1)$. For $m = 2$ and the supercritical case $p > 1/2$, the eventual extinction probability is the smallest solution to $1 - p + ps^2 - s = 0$, which is $\pi = (1 - p)/p$. Therefore, X is a mixture of $U(0, \pi)$ variable with probability $2(1 - p)$ and a point mass at $\pi = (1 - p)/p$ with probability $2p - 1$. In the subcritical case $p < 1/2$, X is a mixture of a uniform $U(0, 1)$ variable with probability $2p$, and point mass at 1 with probability $1 - 2p$.

Example 4.3. $Y \sim \mathcal{P}(\lambda)$, Y is Poisson with parameter λ, and $g(s) = e^{\lambda(s-1)}$. For $\lambda > 1$, $\pi < 1$ is the smallest root of $e^{\lambda(s-1)} = s$; for $\lambda \le 1$, $\pi = 1$. The distribution function of X is

$$F(x) = \begin{cases} 0 & x < 0 \\ \lambda e^{\lambda(x-1)} & 0 \le x < \pi \\ 1 & x \ge \pi. \end{cases}$$

Example 4.4. $Y \sim \mathcal{GG}(b, c)$, Generalized geometric distribution: $P(Y = k) = bc^{k-1}$, $k = 1, 2, \dots$ and $P(Y = 0) = 1 - \sum_{k=1}^{\infty} bc^{k-1} = (1 - b - c)/(1 - c)$, for any $b, c > 0$ such that $b + c < 1$. The standard geometric distribution $\mathcal{G}(p)$ with success probability $p \in (0, 1)$, $p + q = 1$, is the special case $\mathcal{GG}(pq, q)$. Here $g(s) = P(Y = 0) + bs/(1 - cs)$ and can be written as

$$g(s) = (\alpha + \beta s)/(\gamma + \delta s) \tag{4.1}$$

with

$$\alpha = 1 - (b + c), \quad \beta = b - c(1 - c), \quad \gamma = 1 - c, \quad \delta = -c(1 - c). \tag{4.2}$$

This is (according to Athreya and Ney (1972, p. 6)) essentially the only non-trivial example where $g^{(n)}(s)$, and hence $g^{(n)}(0) = q_n$, can be computed explicitly. This example is also discussed in most other texts on branching processes, see e.g. Harris (1963, p. 9), and Karlin and Taylor (1975, p. 402). See also the continuation of this example in Example 6.2, below. Since $EY = b/(1-c)^2$ it follows easily that for $b > (1-c)^2$ the eventual extinction probability is $\pi = [1 - (b + c)]/c(1 - c) = -\alpha/\delta$. In all other cases $\pi = 1$. Here X has c.d.f.

$$F(x) = \begin{cases} 0 & x < 0 \\ b/(1 - cx)^2 & 0 \le x < \pi \\ 1 & x \ge \pi. \end{cases} \tag{4.3}$$

5. Convergence rates of the extinction probabilities for the Galton–Watson process

The purpose of the present section is not to derive new results, but rather to show how well-known results in branching theory have simple proofs by means of stopping rules. We do not strive for the most far-reaching results, and are content with obtaining rates for which $q_n \to \pi$.

Theorem 5.1.

(a) *Supercritical case: If $EY > 1$ then $\pi < 1$ and*

$$0 < \pi - q_n < \pi [g'(\pi)]^n. \tag{5.1}$$

(b) *Subcritical case: If $EY < 1$ (and $P(Y = 0) < 1$), then $\pi = 1$ and*

$$0 < 1 - q_n \leq [EY]^n, \tag{5.2}$$

and the inequality on the right in (5.2) is strict if and only if $P(Y \leq 1) < 1$.

(c) *Critical case: If $EY = 1$, $\mathrm{Var}(Y) = \sigma^2 < \infty$ then*

$$\lim_{n \to \infty} n[1 - g'(q_n)] = 2, \tag{5.3}$$

or equivalently,

$$\lim_{n \to \infty} n(1 - q_n) = 2/\sigma^2. \tag{5.4}$$

More generally, if $EY = 1$ and

$$\lim_{s \to 1^-} (1 - s)g''(s)/[1 - g'(s)] = \alpha \tag{5.5}$$

for some $0 < \alpha \leq 1$, then

$$\lim_{n \to \infty} n[1 - g'(q_n)] = 1 + \alpha^{-1}. \tag{5.6}$$

Proof. (a) According to Theorem 3.1, for X corresponding to Y, $P(X = \pi) = 1 - g'(\pi)$, which is positive. Now consider the suboptimal stopping rule t which stops at the smallest i for which $X_i = \pi$, and if no such i exists, stops at time n anyway. Since this rule is suboptimal, EX_t, the expected value to the statistician using rule t, is at most V_n, but is greater than π times the probability that the value π will be observed, since stopping at $t = n$ with some value smaller than π will still yield a positive expected return. The probability of never observing a value π is $[g'(\pi)]^n$. Thus $\pi(1 - [g'(\pi)]^n) < EX_t \leq V_n = q_n$, from which (5.1) follows.

(b) The proof of (b) is essentially the same as (a), using $\pi = 1$, and $P(X = 1) = 1 - g'(1) = 1 - EY$. Equality in (5.2) holds if and only if the 'suboptimal' rule t is actually optimal. This happens if and only if X is Bernoulli. This case is described in Example 4.1, where $P(Y \leq 1) = 1$, and by the uniqueness of X, as stated in Theorem 3.1, this is the only case.

(c) We draw on the results of Kennedy and Kertz (1991), who show that the asymptotic behaviour of the value sequence V_n for optimal stopping of i.i.d. random variables depends on to which extremal distribution domain X belongs. In the present case, X has no mass at 1, is bounded above by 1, has distribution function $g'(x)$, and the non-zero density $g''(x)$ for $0 < x < 1$. In terms of the given c.d.f. and density, condition (5.5) is equivalent to the condition

for a Type III extreme value distribution given in Theorem 1.6.1. of Leadbetter *et al.* (1983) (see also for example de Haan (1976), Theorem 4 and the remark which follows). Theorem 1.1 of Kennedy and Kertz (1991) now yields (5.6). Note that when $\mathrm{Var}(Y) = \sigma^2 < \infty$ then $g''(1) = \sigma^2$ (since $EY = 1$), and the value of the limit in (5.5) is necessarily 1. Thus (5.3) is the particular case of (5.6) with $\alpha = 1$. Note that by convexity the value in the left-hand side of (5.5) for every fixed s is necessarily less than 1, and hence only α-values less than or equal to one can be obtained as limits in (5.5).

To see that (5.3) is equivalent to (5.4), note that since $q_n \to 1$ and $\lim_{n\to\infty}(1 - g'(q_n))/(1 - q_n) = \sigma^2$ we obtain $\lim_{n\to\infty} n(1 - g'(q_n)) = \lim_{n\to\infty} n(1 - q_n)\sigma^2$.

Remark 5.1. Standard proofs of various parts of Theorem 5.1 can be found in most standard texts on branching processes.

Remark 5.2. We see that the convergence of q_n to π is at a geometric rate in both the supercritical and subcritical cases. It is at the order of $0(1/n)$ in the critical case when $\mathrm{Var}(Y) < \infty$, but $1 - q_n$ converges to zero faster when $\mathrm{Var}(Y) = \infty$.

Remark 5.3. The branching process with $EY = 1$ and $\mathrm{Var}(Y) = \infty$ is studied in Slack (1968). Note that all values of α, $0 < \alpha \le 1$ can be attained as the limit in (5.5), as seen from the following

Example 5.1. For $0 < \alpha \le 1$, and $0 < c \le 1/(1 + \alpha)$, let Y have generating function

$$g(s) = s + (1 - s)^{1+\alpha} c. \tag{5.7}$$

It is easily seen that this corresponds to the distribution

$$P(Y = 0) = c, \qquad P(Y = 1) = 1 - (1 + \alpha)c$$

$$P(Y = k) = (-1)^k c \prod_{j=-1}^{k-2} (\alpha - j)/k!, \quad k = 2, 3, \ldots \tag{5.8}$$

(For $\alpha = 1$ it follows that $P(Y = k) = 0$ for $k > 2$.) Since $g'(1) = 1$ it follows that $EY = 1$ and easy arithmetic yields (5.5). Here (5.6) can be stated as

$$\lim_{n\to\infty} n(1 - q_n)^\alpha = (c\alpha)^{-1} \tag{5.9}$$

and shows that q_n tends to 1 faster, the smaller α. (Note that for $\alpha = 1$ one has $\mathrm{Var}(Y) = 2c$ and (5.9) agrees with (5.4) in this case.)

Remark 5.4. Though in most natural situations the limit in (5.5) does exist, one can exhibit generating functions for which the limit in (5.5) fails to exist. One such construction is a function having a coefficient sequence which essentially alternates between the coefficient sequences of generating functions of the form (5.7) for two different values of α.

6. Inhomogeneous branching processes

In this section we consider the inhomogeneous branching process, as presented in Section 2(b). Here the offspring distribution in generation i is Y_i, where the Y_i need not have identical distributions. To each Y_i there is a corresponding X_i defined through (3.1), where g there is replaced by g_i, and π by π_i (where π_i is the eventual extinction probability of an

ordinary Galton–Watson process with fixed offspring distribution Y_i). Now consider an optimal stopping problem where $X_1, \ldots, X_n$ are observed sequentially. From (2.2) and (2.3) it follows that the value V_1^n to the statistician, of this sequence is

$$V_1^n = h_1(h_2(\cdots h_n(0))). \tag{6.1}$$

If we denote more generally

$$h^{(n)}(a) = h_1(h_2(\cdots h_n(a))) \tag{6.2}$$

then, using (2.9), we can generalize Theorem 3.1 and (3.5) as follows.

Theorem 6.1. *Suppose $\pi_1 \geq \pi_2 \geq \cdots \geq \pi_n$. Then*

$$h^{(n)}(a) = g^{(n)}(a) \quad \text{for} \quad 0 \leq a \leq \pi_n,$$

and thus also $V_1^n = \tilde{q}_n$.

The proof is straightforward and hence omitted.

Inhomogeneous Galton–Watson processes have been studied quite extensively in the literature. The earlier references are Jagers (1974) and Jirina (1976). See also Section 3.5 in Jagers (1975). One of the latest references we have come across is d'Souza (1995). See also all related references mentioned there. All papers deal with various aspects of the limiting value of Z_n under different assumptions on the Y_i's. The following theorem has a very simple 'stopping rule' proof.

Theorem 6.2. *Suppose $\pi_i = \pi_0$ for all $i = 1, 2, \ldots$, and denote $r_i = P(Y_i \neq 1)$. Then $\tilde{\pi} \leq \pi_0$ with*

$$\tilde{\pi} = \pi_0 \quad \text{if and only if} \quad \sum_{i=1}^{\infty} r_i = \infty. \tag{6.3}$$

Proof. Let X_i correspond to Y_i through the relation (3.1). By Theorem 6.1, $\tilde{q}_n = V_1^n$, and hence $V_\infty = \lim_{n\to\infty} V_1^n = \lim_{n\to\infty} \tilde{q}_n = \tilde{\pi}$. Since by (3.1) $X_i \leq \pi_0$, $i = 1, 2, \ldots$, $\tilde{\pi} = V_\infty \leq \pi_0$.

We will show that $\tilde{\pi} = \pi_0$ if and only if for all $0 < \varepsilon < \pi_0$,

$$\sum_{i=1}^{\infty}[1 - g_i'(\pi_0 - \varepsilon)] = \infty, \tag{6.4}$$

and then prove that (6.4) is equivalent to the condition $\sum r_i = \infty$. Note that $P(X_i \geq \pi_0 - \varepsilon) = 1 - g_i'(\pi_0 - \varepsilon)$. Thus if (6.4) holds then $P(X_i \geq \pi_0 - \varepsilon$ infinitely often$) = 1$. Hence, for the rule $t = \inf\{i : X_i \geq \pi_0 - \varepsilon\}$, we have $P(t < \infty) = 1$, and the value for this rule, EX_t, is at least $\pi_0 - \varepsilon$, and hence $\pi_0 - \varepsilon \leq V_\infty \leq \pi_0$. Since this is true for every $\varepsilon > 0$ it follows that $\tilde{\pi} = V_\infty = \pi_0$. Conversely, if (6.4) fails for some $0 < \varepsilon_0 < \pi_0$ then by the Borel–Cantelli lemma, $P(X_i \geq \pi_0 - \varepsilon_0$ infinitely often$) < 1$, and hence there is positive probability of never seeing a value greater than $\pi_0 - \varepsilon$, thus the supremum of the expected return over all stopping rules is less than π_0, that is, $\tilde{\pi} < \pi_0$.

It remains to verify that (6.4) is equivalent to the condition $\sum r_i = \infty$. Let $P(Y_i = k) = p_{ik}$, $k = 2, 3, \ldots$. Then

$$g_i'(s) = 1 - r_i + \sum_{k \geq 2} k p_{ik} s^{k-1}.$$

Note that for any $k \geq 1$, $(\pi_0 - \varepsilon)^k \leq (\pi_0 - \varepsilon)\pi_0^{k-1} = (1 - \varepsilon/\pi_0)\pi_0^k$, and also that $g_i'(\pi_0) \leq 1$; thus

$$1 - g_i'(\pi_0 - \varepsilon) = r_i - \sum_{k \geq 2} k p_{ik}(\pi_0 - \varepsilon)^{k-1} \geq r_i - (1 - \varepsilon/\pi_0)\sum_{k \geq 2} k p_{ik}\pi_0^{k-1}$$

$$= r_i - (1 - \varepsilon/\pi_0)[g_i'(\pi_0) - 1 + r_i] \geq r_i - (1 - \varepsilon/\pi_0)r_i = (\varepsilon/\pi_0)r_i. \quad (6.5)$$

Thus, if $\sum r_i = \infty$, (6.4) holds for every $0 < \varepsilon < \pi_0$ (and $\tilde{\pi} = \pi_0$). On the other hand, from the first equality in (6.5) it follows that $1 - g_i'(\pi_0 - \varepsilon) \leq r_i$. Thus $\sum r_i < \infty$ implies that the sum in (6.4) converges.

Remark 6.1. Suppose $EY_i \leq 1$ for all i, and $\sum_{i=1}^{\infty}[1 - EY_i] = \infty$. Since $1 - EY_i \leq r_i$, $\sum_{i=1}^{\infty} r_i = \infty$ and $\tilde{\pi} = 1$ follows.
  Since $EY_i \leq 1$, one has $P(X_i = 1) = 1 - g'(1) = 1 - EY_i$. Thus the probability that $X_i = 1$ infinitely often, equals one, so the rule which stops for the smallest i for which $X_i = 1$, stops with probability 1. Thus the value $V_\infty = 1$ is, in this case, attainable by a stopping rule t with $P(t < \infty) = 1$. In all other situations where $\sum r_i = \infty$, the value $V_\infty = 1$ is not attainable, and only ε-optimal stopping rules exist.

Remark 6.2. Note that $\pi_i = \pi_0$ for all i implies by (2.9) that $g^{(n)}(\pi_0) = \pi_0$ also. Thus unlike the situation in the homogeneous Galton–Watson process where $\lim_{n \to \infty} g^{(n)}(s) = \pi$ for $0 \leq s \leq \pi$, in the inhomogeneous case, it may happen that even though $\lim_{n \to \infty} g^{(n)}(s)$ exists for all $0 \leq s \leq 1$, this limit need not equal π_0 for $0 \leq s < \pi_0$, unless $\sum r_i = \infty$. A similar remark is true also for the case $\pi_0 = 1$.

Example 6.1. Let Y_i take the values 0, 1 and 2 only, with probabilities $P(Y_i = 0) = r_i/3$, $P(Y_i = 1) = 1 - r_i$ and $P(Y_i = 2) = 2r_i/3$, where $0 < r_i \leq 1$. Here $g_i(s) = r_i/3 + (1-r_i)s + 2r_i s^2/3$, and it is easily checked that $\pi_i = 1/2$ for all i. Note that here $EY_i = 1 + r_i/3$. Since $EZ_n = \prod_{i=1}^{n} EY_i$, the condition $\sum r_i = \infty$ is equivalent to $\lim_{n \to \infty} EZ_n = \infty$.

Example 6.2. As in Keiding and Nielsen (1975), let Y_i have the generalized geometric distribution, $\mathcal{GG}(b_i, c_i)$, as described in Example 4.4; hence, Y_i has generating function as in (4.1)

$$g_i(s) = (\alpha_i + \beta_i s)/(\gamma_i + \delta_i s) \quad (6.6)$$

where the constants are defined as in (4.2). Then it can be verified by induction that

$$g^{(n)}(s) = (\alpha^{(n)} + \beta^{(n)} s)/(\gamma^{(n)} + \delta^{(n)} s), \quad (6.7)$$

and the values of $\alpha^{(n)}$, $\beta^{(n)}$, $\gamma^{(n)}$ and $\delta^{(n)}$ can be obtained explicitly. We shall consider in detail the case where all Y_i are 'critical', i.e. $b_i = (1 - c_i)^2$. For this case let

$$S_i^{(n)} = \sum c_{k_1} \cdots c_{k_i} \quad (6.8)$$

where the summation is over all $1 \leq k_1 < \cdots < k_i \leq n$. Set $S_0^{(n)} = 1$. Then one can verify that

$$\alpha^{(n)} = \sum_{j=1}^{n}(-1)^{j-1} j S_j^{(n)}, \qquad\qquad \beta^{(n)} = \sum_{j=0}^{n}(-1)^j (j + 1) S_j^{(n)}$$

$$\gamma^{(n)} = 1 + \sum_{j=2}^{n}(-1)^{j-1}(j - 1) S_j^{(n)}, \qquad \delta^{(n)} = -\alpha^{(n)}.$$

$$\qquad\qquad\qquad\qquad\qquad\qquad\qquad\qquad\qquad\qquad\qquad\qquad\qquad (6.9)$$

Clearly here $\tilde{q}_n = \alpha^{(n)}/\gamma^{(n)}$. It follows from (6.8) and (6.9) that for any n, all $n!$ permutations of the order of the Y_is yield the same distribution for the nth generation, Z_n. Note that here $P(Y_i = 1) = 1 - r_i = (1 - c_i)^2$ which implies that $r_i = c_i(2 - c_i)$. Thus, by Theorem 6.2, $\tilde{\pi} = 1$ if and only if $\sum c_i = \infty$.

It is of interest to note that the permutation invariance mentioned above can be generalized. Let Y_1 and Y_2 have generating function of the form (4.1). Then the generating function of Z_2 is (see (2.9))

$$g_1(g_2(s)) = \frac{(\alpha_1\gamma_2 + \beta_1\alpha_2) + (\alpha_1\delta_2 + \beta_1\beta_2)s}{(\gamma_1\gamma_2 + \delta_1\alpha_2) + (\gamma_1\delta_2 + \delta_1\beta_2)s},$$

and it can then be verified that $g_1(g_2(s)) = g_2(g_1(s))$ if and only if $\alpha_1/\delta_1 = \alpha_2/\delta_2$. But for $\pi_i < 1$ one has $-\alpha_i/\delta_i = \pi_i$, thus the order does not matter if and only if $\pi_1 = \pi_2$. This generalizes immediately for composing n such generating functions, and shows that the order of the Y_is does not matter if and only if all $\pi_i = \pi_0 < 1$ in this case. We do not know if this property has been observed earlier. Translating to optimal stopping, we have obtained a sequence of non identically distributed variables for which the optimal stopping value is the same, no matter in which order the variables appear.

It is easy to show, by working out the distribution of Z_2 in Example 6.1, that even though $\pi_1 = \pi_2 = 1/2$ there, the Y_is there do not have the permutation invariance property.

7. Connections to prophet values and prophet inequalities

When not all π_i are equal, or when the necessary condition of Theorem 6.2 fails, one may still obtain meaningful, though sometimes crude, lower and upper bounds on $\tilde{\pi}$ through the use of suboptimal stopping rules, the 'prophet' value and the 'prophet inequality.' If EX_t is the value of any (optimal or suboptimal) stopping rule t, for the n-horizon case, then $EX_t \leq V_n = \tilde{q}_n \leq V_\infty = \tilde{\pi}$, and if EX_t is the value of a suboptimal rule for the infinite horizon case, $EX_t \leq V_\infty = \tilde{\pi}$, yielding lower bounds on $\tilde{q}_n$ and $\tilde{\pi}$. Let $V_p^n = E(\max(X_1, \ldots, X_n))$ and $V_p^\infty = \lim_{n\to\infty} V_p^n$. V_p^n and V_p^∞ are called 'prophet values'. The term 'prophet value' stems from the fact that an individual with complete foresight of the future would simply select the largest X_i value in the sequence, and obtain the expected return V_p, the 'prophet value'. The prophet values V_p^n and V_p^∞ are usually much easier to compute than the optimal stopping value. Since the value of any stopping rule is necessarily less than or equal to that of the prophet, we have the upper bound $\tilde{q}_n = V_n \leq V_p^n \leq V_p^\infty$ and hence $\tilde{\pi} \leq V_p^\infty$. In addition, the prophet value can also be used to obtain a lower bound on $\tilde{\pi}$. It is well-known (see e.g. Hill and Kertz (1981)) that for a sequence of non-negative independent random variables $V_p^n < 2V_n$, and thus $V_p^n/2 < V_n = \tilde{q}_n \leq \tilde{\pi}$ serves as a lower bound on $\tilde{q}_n$ and $\tilde{\pi}$. Letting $n \to \infty$, we see that $V_p^\infty/2$ is also a lower bound on $\tilde{\pi}$.

Example 7.1. Consider Example 6.1 with $\sum r_i < \infty$. Since $g_i'(0) = 1 - r_i$, and $\pi_i = 1/2$, the X_i corresponding to Y_i has mass $1 - r_i$ at zero and is bounded above by $\frac{1}{2}$. Hence, the variable X_i^* where $P(X_i^* = 0) = 1 - r_i$ and $P(X_i^* = 1/2) = r_i$ is stochastically larger than X_i, and therefore the prophet value for the X_i^* sequence is an upper bound on the prophet value for the X_i sequence. The prophet value for the X_i^*-sequence is $\frac{1}{2}$ the probability that any of the X_i^* variables equals $\frac{1}{2}$, i.e. $(1/2)[1 - \prod_{i=1}^{\infty}(1 - r_i)]$. To obtain a lower bound on $\tilde{\pi}$, consider the suboptimal rule which stops for the smallest i such that $X_i > 0$. It should be noted that since $\sum r_i < \infty$, this rule does not stop with probability one unless $r_i = 1$ for some i. Even if $r_i < 1$ for all i the value of this 'rule' equals the limit of the value of the rule t_n which stops for the smallest i such that $X_i > 0$, and stops at time n if no positive X_i is observed up to and including

time n. The conditional expected return for stopping at X_i, given $X_i > 0$, is $\frac{1}{3}$. Thus the value of this rule is $(1/3)[1 - \prod_{i=1}^{\infty}(1 - r_i)]$. A different lower bound can be obtained through the rule which stops for the smallest i such that $X_i = 1/2$, if such an i exists. Its expected return is $(1/2)[1 - \prod_{i=1}^{\infty}(1 - r_i/3)]$. Thus

$$\max\left\{\frac{1}{2}\left[1 - \prod_{i=1}^{\infty}(1 - r_i/3)\right], \frac{1}{3}\left[1 - \prod_{i=1}^{\infty}(1 - r_i)\right]\right\} \leq \tilde{\pi} < \frac{1}{2}\left[1 - \prod_{i=1}^{\infty}(1 - r_i)\right].$$

For example, if $r_i = 1/(i + 1)^2$ we have

$$\prod_{i=1}^{\infty}(1 - r_i) = \lim_{n\to\infty}\prod_{i=1}^{n}\frac{i(i + 2)}{(i + 1)^2} = \lim_{n\to\infty}\frac{(n + 2)}{2(n + 1)} = \frac{1}{2},$$

so that $1/6 \leq \tilde{\pi} \leq 1/4$. (Recall that $\pi_0 = 1/2$.)

We have shown how the correspondence between Y and X can be used to obtain information about branching processes from computations involving an optimal stopping problem. The following theorem shows how the correspondence can be applied in the other direction.

Theorem 7.1. *Let* $Y \in \mathcal{Y}$ *with* $EY \leq 1$*, and let* X *be the corresponding random variable with distribution given in (3.1). With* $X_1, \ldots, X_n$ *i.i.d. random variables distributed like* X*, let* $X_n^* = \max(X_1, \ldots, X_n)$*. Then* X_n^* *corresponds to a* $Y_n^* \in \mathcal{Y}$*, and the prophet value* EX_n^* *can be computed using*

$$EX_n^* = P(Y_n^* = 0). \tag{7.1}$$

Proof. The distribution function of $X_n^* = \max(X_1, \ldots, X_n)$ is

$$F_n^*(x) = \begin{cases} 0 & x < 0 \\ [g'(x)]^n & 0 \leq x < 1 \\ 1 & 1 \leq x. \end{cases} \tag{7.2}$$

Clearly $k(x) = [g'(x))]^n$ satisfies condition (i) of Remark 3.5. Now since $g'(x) \leq g'(1) = EY \leq 1$, $[g'(x)]^n \leq g'(x)$ for $0 < x < 1$ and $\int_0^1 [g'(x)]^n \, dx \leq \int_0^1 g'(x) \, dx < 1$. Hence

$$g^*(s) = \int_0^s k(x) \, dx + \left(1 - \int_0^1 k(x) \, dx\right) \tag{7.3}$$

further satisfies $g^*(0) > 0$ and $g^*(1) = 1$. Since here $\pi^* = 1$, (where π^* is the smallest root such that $g^*(s) = s$), condition (ii) (b) of Remark 3.5, $g(\pi) = \pi$, is equivalent to (ii) (a).

Remark 7.1. If $EY > 1$ i.e. $\pi < 1$, then $\max(X_1, \ldots, X_n)$ does not correspond to any $Y^* \in \mathcal{Y}$ since the distribution corresponding to (7.2) for this case cannot satisfy (ii) (a) and (b) of Remark 3.5 simultaneously.

Remark 7.2. When $EY \leq 1$, then $EY_n^* = \mathrm{d}g^*(x)/\mathrm{d}x|_1 = k(1) = [g'(1)]^n = [EY]^n$.

For the cases below which illustrate Theorem 7.1, the given $g(x)$ is sufficiently unaltered upon differentiation, taking powers, and integration that $g^*(x)$ of (7.3) corresponds to a variable Y_n^* of the same 'type' as the original Y, with a mass at zero according to the constant term in (7.3).

Example 7.2. Let X be the variable corresponding to the Y of Example 4.2 with $p \leq 1/m$, where $g'(x) = mpx^{m-1}$. Hence $k(x) = (mpx^{m-1})^n$ for $0 \leq x < 1$ and hence

$$g^*(x) = (mp)^n x^{n(m-1)+1}/[n(m-1)+1] + (1-(mp)^n/[n(m-1)+1]),$$

and the prophet value $EX_n^* = P(Y_n^* = 0) = g^*(0) = 1 - (mp)^n/[n(m-1)+1]$. Note that Y_n^* takes on only the two values 0 and $n(m-1)+1$, and hence is of the same type as the original Y.

Example 7.3. Let X correspond to a Poisson $\mathcal{P}(\lambda)$ variable Y, as in Example 4.3, with $\lambda \leq 1$. Then $k(x) = (\lambda e^{\lambda(x-1)})^n$, so

$$g^*(x) = (\lambda^{n-1}/n)e^{n\lambda(x-1)} + (1 - \lambda^{n-1}/n),$$

and hence Y_n^* is a mixture of a Poisson $\mathcal{P}(n\lambda)$ random variable with probability λ^{n-1}/n, and the constant 0 with probability $(1 - \lambda^{n-1}/n)$. Thus the prophet value EX_n^* can be computed by

$$P(Y_n^* = 0) = 1 - \frac{\lambda^{n-1}}{n}(1 - e^{-n\lambda}).$$

Example 7.4. Let X have distribution (4.4) with $p \in [0, 1/2]$, $q = 1 - p$, $b = pq$, $c = p$, and $\pi = 1$. It follows that Y is geometric $\mathcal{G}(p)$, and $g(x) = q/(1 - px)$. Hence $k(x) = (pq/(1 - px)^2)^n$ and we may write

$$g^*(x) = \frac{p^{n-1}}{(2n-1)q^{n-1}}\left(\frac{q}{1-px}\right)^{2n-1} + \left(1 - \frac{p^{n-1}}{(2n-1)q^{n-1}}\right).$$

Hence, Y_n^* is a mixture of a sum of $2n-1$ independent $\mathcal{G}(p)$ variables, that is, a negative binomial, with probability $(p/q)^{n-1}/(2n-1)$, and the constant 0 with probability $1-(p/q)^{n-1}/(2n-1)$. Thus the prophet value EX_n^* equals

$$P(Y_n^* = 0) = q^n p^{n-1}/(2n-1) + (1 - (p/q))^{n-1}/(2n-1)).$$

Remark 7.3. In a similar way it can also be shown that in the inhomogeneous case, when $EY_i \leq 1$ for all $i = 1, \ldots, n$, the prophet variable $X_n^* = \max(X_1, \ldots, X_n)$ again corresponds to a $Y^* \in \mathcal{Y}$.

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